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Today (45 minutes):

1. Comparing Generative Models

2. Metrics

3. Fast Fréchet Inception Distance

4. What is it Good For? 🎜

Comparing Generative Models

Which one is better?

"Real"

$x_1, \ldots, x_n \sim P_{\text{real}}$



Which one is better?

"Real"
 "Fake 1"

$$x_1, \ldots, x_n \sim P_{real}$$
 $x_1^{(1)}, \ldots, x_m^{(1)} \sim P_{G_1}$

 Image: Constraint of the second s

Which one is better?

"Real"
 "Fake 1"
 "Fake 2"

$$x_1, \ldots, x_n \sim P_{real}$$
 $x_1^{(1)}, \ldots, x_m^{(1)} \sim P_{G_1}$
 $x_1^{(2)}, \ldots, x_\ell^{(2)} \sim P_{G_2}$

 Image: Image:

1. Fast



- 1. Fast
- 2. Diversity

- 1. Fast
- 2. Diversity
- 3. Classifiable



- 1. Fast
- 2. Diversity
- 3. Classifiable
- 4. Translation invariant



Metrics

First Idea: Inception Score¹

Salimans, T., Goodfellow, I., Zaremba, W., Cheung, V., Radford, A. and Chen, X., 2016. Improved techniques for training gans. arXiv preprint arXiv:1606.03498.

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(1) (2)

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$$IS(X) = \exp\{ \mathbb{E}_{x} [KL(p(y | x) || p(y))] \}$$
(1)
(2)

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Inception Score

$$IS(X) = \exp\{\underbrace{H(y)}_{\text{Maximize}} - \underbrace{\mathbb{E}_{x}[H(y|x)]}_{\text{Minimize}}\}$$
(2)



Correlates with human judgement but doesn't take *P*_{real} into account!

Second Idea: Fréchet Inception Distance²

Heusel, M., Ramsauer, H., Unterthiner, T., Nessler, B. and Hochreiter, S., 2017. Gans trained by a two time-scale update rule converge to a local nash equilibrium. arXiv preprint arXiv:1706.08500.

Idea: Compare Inception network encodings between *P*_{real} and *P*_{fake}.

Given means μ_r , μ_f and covariances Σ_r , Σ_f of Inception encodings, the Fréchet Inception Distance (FID) is defined as

$$\operatorname{FID}(X_r, X_f) = W_2^2 \left(\mathcal{N}\{\mu_r, \Sigma_r\}, \mathcal{N}\{\mu_f, \Sigma_f\} \right)$$
(3)

(4)

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$$= \underbrace{\|\mu_r - \mu_f\|_2^2}_{\mathcal{O}(d)} + -2$$
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$$= \underbrace{\|\mu_r - \mu_f\|_2^2}_{\mathcal{O}(d)} + \underbrace{\operatorname{Tr}[\Sigma_r]}_{\mathcal{O}(d)} + \underbrace{\operatorname{Tr}[\Sigma_f]}_{\mathcal{O}(d)} - 2$$
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Today this is state-of-the-art.

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Input : Σ_r , Σ_f Output: $\operatorname{Tr}[C] = \operatorname{Tr} \left[\sqrt{\Sigma_r \Sigma_f} \right]$ 1 $Q, V \leftarrow SchurDecompose(A);$ 2 $U \leftarrow TriangSqrt(V);$

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/* QVQT = A */ /* V = U² */ /* C = $\sqrt{\Sigma_{r}\Sigma_{f}}$ */

Input : Σ_r , Σ_f Output: $\operatorname{Tr}[C] = \operatorname{Tr}\left[\sqrt{\Sigma_r \Sigma_f}\right]$ 1 $Q, V \leftarrow SchurDecompose(A)$; 2 $U \leftarrow TriangSqrt(V)$; 3 $C \leftarrow QUQ^{\intercal}$; 4 return $\operatorname{Tr}[C]$;

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$$/* \ QVQ^{T} = A \ */$$
$$/* \ V = U^{2} \ */$$
$$/* \ C = \sqrt{\Sigma_{r}\Sigma_{f}} \ */$$

Line [1-3] each takes cubic time!

Idea 3: Don't compute $Tr\left[\sqrt{\Sigma_r \Sigma_f}\right]$, use *eigenvalues* instead.³

Mathiasen, A. and Hvilshøj, F., 2020. Fast Fréchet Inception Distance. arXiv preprint arXiv:2009.14075.

Lemma 1 Tr[\sqrt{A}] = $\sum_{i} |\sqrt{\lambda_i(A)}|$. ⁴

⁴There are some nuances here, please refer to paper for full details.

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Lemma 2 Computing eigenvalues of $d \times d$ matrix A takes $\mathcal{O}(d^3)$ time. (similar time to compute \sqrt{A})

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The non-zero eigenvalues of AB are equal to those of BA, as long as the products are square. ⁵

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High level idea: Construct "small" matric M such that $\lambda_i(M)$ satisfy $\sum_i |\sqrt{\lambda_i(M)}| = \text{Tr}[\sqrt{\Sigma_r \Sigma_f}]$. When M is sufficiently small, computing eigenvalues will be faster than computing $\sqrt{\Sigma_r \Sigma_f}$ explicitly.

Stack the *m* fake encoded samples into a $d \times m$ matrix X_{f} .

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 where $C_f = \frac{1}{\sqrt{m-1}} \left(X_f - \mu_r \mathbf{1}_m \right)$ (5)

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$$\boldsymbol{\Sigma}_{f} = C_{f}C_{f}^{\mathsf{T}} \quad \text{where } C_{f} = \frac{1}{\sqrt{m-1}} \left(X_{f} - \mu_{r} \mathbf{1}_{m} \right) \tag{5}$$

Then

$$\Sigma_r \Sigma_f = \Sigma_r C_f C_f^{\mathsf{T}} \tag{6}$$

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Eigenvalue computations go from $\mathcal{O}(d^3)$ to $\mathcal{O}(m^3)$ (Lemma 2).

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Using Lemma 3:



Eigenvalue computations go from $\mathcal{O}(d^3)$ to $\mathcal{O}(m^3)$ (Lemma 2). Finally due to Lemma 1:

$$\operatorname{Tr}\left[\sqrt{\Sigma_{r}\Sigma_{f}}\right] = \sum_{i=1}^{m-1} |\sqrt{\lambda_{i}(C_{f}^{\mathsf{T}}\Sigma_{r}C_{f})}|$$
(8)

Overall, we get runningtime

$$\operatorname{FID} = \underbrace{\|\mu_r - \mu_f\|_2^2}_{\mathcal{O}(d)} + \underbrace{\operatorname{Tr}[\Sigma_r + \Sigma_f]}_{\mathcal{O}(d)} - 2\sum_{i=1}^{m-1} |\underbrace{\sqrt{\lambda_i(C_f^{\mathsf{T}}\Sigma_r C_f)}}_{\mathcal{O}(d^2m + m^3)}| \quad (9)$$

What is it Good For? 🞜

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Example 4

For GANs on ImageNet, test size (*n*) is 10 000, encodings (*d*) are 2048, and batch size (*m*) is typically 128.

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Set's use FID for optimizations!





GAN









What will happen if we just optimize for FID?

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